



## BAXMC: a CEGAR approach to Max#SAT

**Thomas Vigouroux**   Cristian Ene   David Monniaux  
Laurent Mounier   Marie-Laure Potet

VERIMAG - UGA

October 20, 2022

# fmcad.<sup>22</sup>

# Introduction

## Context

In security: the question of *quantitative reachability*.

```
atk = input()  
if atk == x and x + y < XMAX:  
    win() # trigger / exploit vulnerability
```

# Introduction

## Context

In security: the question of *quantitative reachability*.

```
atk = input()  
if atk == x and x + y < XMAX:  
    win() # trigger / exploit vulnerability
```

$$\phi \triangleq atk = x \wedge x + y \leq XMAX$$

# Introduction

## Context

In security: the question of *quantitative reachability*.

```
atk = input()
if atk == x and x + y < XMAX:
    win() # trigger / exploit vulnerability
```

$$\phi \triangleq atk = x \wedge x + y \leq XMAX$$

## Question

Which answer (*atk* value) maximizes the winning probability ?

# Introduction

## Context

In security: the question of *quantitative reachability*.

```
atk = input()
if atk == x and x + y < XMAX:
    win() # trigger / exploit vulnerability
```

$$\phi \triangleq atk = x \wedge x + y \leq XMAX$$

## Question

Which answer (*atk* value) maximizes the winning probability ?

Useful applications:

- ▶ Comparing bugs quantitatively
- ▶ Measure the information leakage of a program

# Introduction

## Definition of the problem

### Definition (Max#SAT)

Given  $\phi(\mathcal{X}, \mathcal{Y}, \mathcal{Z})$ , find a witness  $x_m$  that maximizes the following:

$$|\phi(x_m, \mathcal{Y}, \mathcal{Z})| \triangleq |\{y \mid \exists z . \phi(x_m, y, z)\}|$$

### Example

With  $\mathcal{X} = \{a, b\}$ ,  $\mathcal{Y} = \{c\}$ ,  $\mathcal{Z} = \{d\}$ :

$$\phi = (\neg a \vee c) \wedge (a \vee \neg b) \wedge (\neg b \vee d)$$

# Introduction

## Definition of the problem

### Definition (Max#SAT)

Given  $\phi(\mathcal{X}, \mathcal{Y}, \mathcal{Z})$ , find a witness  $x_m$  that maximizes the following:

$$|\phi(x_m, \mathcal{Y}, \mathcal{Z})| \triangleq |\{y \mid \exists z . \phi(x_m, y, z)\}|$$

### Example

With  $\mathcal{X} = \{a, b\}$ ,  $\mathcal{Y} = \{c\}$ ,  $\mathcal{Z} = \{d\}$ :

$$\phi = (\neg a \vee c) \wedge (a \vee \neg b) \wedge (\neg b \vee d)$$

Model $x$	Resulting formula	# Models over $\mathcal{Y}$
$a \wedge b$	$c \wedge d$	1

# Introduction

## Definition of the problem

### Definition (Max#SAT)

Given  $\phi(\mathcal{X}, \mathcal{Y}, \mathcal{Z})$ , find a witness  $x_m$  that maximizes the following:

$$|\phi(x_m, \mathcal{Y}, \mathcal{Z})| \triangleq |\{y \mid \exists z . \phi(x_m, y, z)\}|$$

### Example

With  $\mathcal{X} = \{a, b\}$ ,  $\mathcal{Y} = \{c\}$ ,  $\mathcal{Z} = \{d\}$ :

$$\phi = (\neg a \vee c) \wedge (a \vee \neg b) \wedge (\neg b \vee d)$$

Model $x$	Resulting formula	# Models over $\mathcal{Y}$
$a \wedge b$	$c \wedge d$	1
$a \wedge \neg b$	$c$	1
$\neg a \wedge b$	$\perp$	0
$\neg a \wedge \neg b$	$\top$	2



# Introduction

## Definition of the problem

### Definition (Max#SAT)

Given  $\phi(\mathcal{X}, \mathcal{Y}, \mathcal{Z})$ , find a witness  $x_m$  that maximizes the following:

$$|\phi(x_m, \mathcal{Y}, \mathcal{Z})| \triangleq |\{y \mid \exists z . \phi(x_m, y, z)\}|$$

### Example

With  $\mathcal{X} = \{a, b\}$ ,  $\mathcal{Y} = \{c\}$ ,  $\mathcal{Z} = \{d\}$ :

$$\phi = (\neg a \vee c) \wedge (a \vee \neg b) \wedge (\neg b \vee d)$$

Model $x$	Resulting formula	# Models over $\mathcal{Y}$
$a \wedge b$	$c \wedge d$	1
$a \wedge \neg b$	$c$	1
$\neg a \wedge b$	$\perp$	0
$\neg a \wedge \neg b$	$\top$	2

# A CEGAR-based algorithm

Inspired by CEGAR methods: the formula is refined towards the search of better solutions.

## Key Insight

It is possible to quickly overapproximate the maximum model counting of a subspace.

# A CEGAR-based algorithm

Inspired by CEGAR methods: the formula is refined towards the search of better solutions.

## Key Insight

It is possible to quickly overapproximate the maximum model counting of a subspace.

If this overapproximation is below the current known maximum  
→ we can exclude the sub-space from future search.

# A CEGAR-based algorithm

## Main algorithm

Takes  $\phi(\mathcal{X}, \mathcal{Y}, \mathcal{Z})$  as input and returns  $x_m$ .

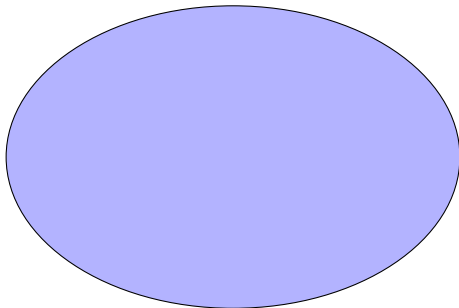
1. Find an  $x$  candidate
2. *Generalize* it to a partial witness  $x|_{\mathcal{E}}$  such that  $|\phi(x|_{\mathcal{E}}, \mathcal{Y}, \mathcal{Z})|$  is close (from below) to the current maximum
3. Exclude the sub-space  $x|_{\mathcal{E}}$  from the future search
4. Loop

# A CEGAR-based algorithm

## Main algorithm

Takes  $\phi(\mathcal{X}, \mathcal{Y}, \mathcal{Z})$  as input and returns  $x_m$ .

1. Find an  $x$  candidate
2. *Generalize* it to a partial witness  $x|_{\mathcal{E}}$  such that  $|\phi(x|_{\mathcal{E}}, \mathcal{Y}, \mathcal{Z})|$  is close (from below) to the current maximum
3. Exclude the sub-space  $x|_{\mathcal{E}}$  from the future search
4. Loop

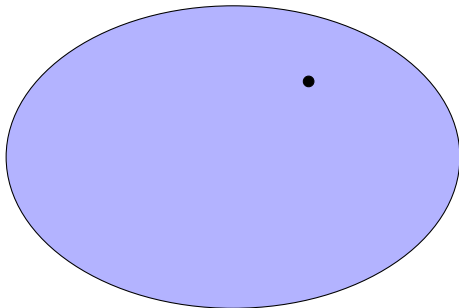


# A CEGAR-based algorithm

## Main algorithm

Takes  $\phi(\mathcal{X}, \mathcal{Y}, \mathcal{Z})$  as input and returns  $x_m$ .

1. Find an  $x$  candidate
2. Generalize it to a partial witness  $x|_{\mathcal{E}}$  such that  $|\phi(x|_{\mathcal{E}}, \mathcal{Y}, \mathcal{Z})|$  is close (from below) to the current maximum
3. Exclude the sub-space  $x|_{\mathcal{E}}$  from the future search
4. Loop

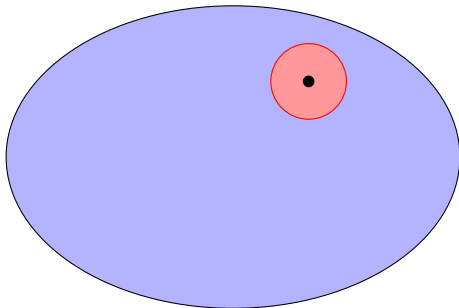


# A CEGAR-based algorithm

## Main algorithm

Takes  $\phi(\mathcal{X}, \mathcal{Y}, \mathcal{Z})$  as input and returns  $x_m$ .

1. Find an  $x$  candidate
2. *Generalize* it to a partial witness  $x|_{\mathcal{E}}$  such that  $|\phi(x|_{\mathcal{E}}, \mathcal{Y}, \mathcal{Z})|$  is close (from below) to the current maximum
3. Exclude the sub-space  $x|_{\mathcal{E}}$  from the future search
4. Loop

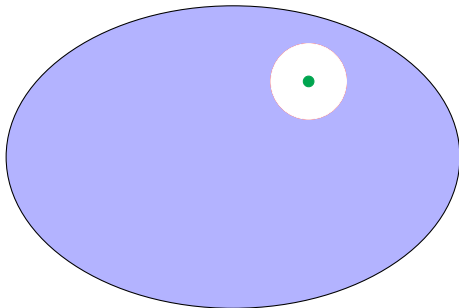


# A CEGAR-based algorithm

## Main algorithm

Takes  $\phi(\mathcal{X}, \mathcal{Y}, \mathcal{Z})$  as input and returns  $x_m$ .

1. Find an  $x$  candidate
2. *Generalize* it to a partial witness  $x|_{\mathcal{E}}$  such that  $|\phi(x|_{\mathcal{E}}, \mathcal{Y}, \mathcal{Z})|$  is close (from below) to the current maximum
3. **Exclude the sub-space**  $x|_{\mathcal{E}}$  from the future search
4. Loop



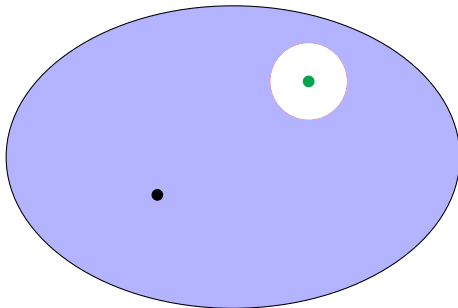


# A CEGAR-based algorithm

## Main algorithm

Takes  $\phi(\mathcal{X}, \mathcal{Y}, \mathcal{Z})$  as input and returns  $x_m$ .

1. Find an  $x$  candidate
2. Generalize it to a partial witness  $x|_{\mathcal{E}}$  such that  $|\phi(x|_{\mathcal{E}}, \mathcal{Y}, \mathcal{Z})|$  is close (from below) to the current maximum
3. Exclude the sub-space  $x|_{\mathcal{E}}$  from the future search
4. Loop

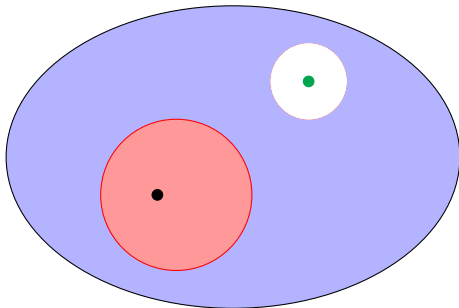


# A CEGAR-based algorithm

## Main algorithm

Takes  $\phi(\mathcal{X}, \mathcal{Y}, \mathcal{Z})$  as input and returns  $x_m$ .

1. Find an  $x$  candidate
2. *Generalize* it to a partial witness  $x|_{\mathcal{E}}$  such that  $|\phi(x|_{\mathcal{E}}, \mathcal{Y}, \mathcal{Z})|$  is close (from below) to the current maximum
3. Exclude the sub-space  $x|_{\mathcal{E}}$  from the future search
4. Loop

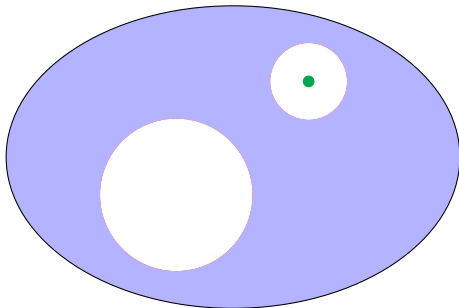


# A CEGAR-based algorithm

## Main algorithm

Takes  $\phi(\mathcal{X}, \mathcal{Y}, \mathcal{Z})$  as input and returns  $x_m$ .

1. Find an  $x$  candidate
2. *Generalize* it to a partial witness  $x|_{\mathcal{E}}$  such that  $|\phi(x|_{\mathcal{E}}, \mathcal{Y}, \mathcal{Z})|$  is close (from below) to the current maximum
3. **Exclude the sub-space**  $x|_{\mathcal{E}}$  from the future search
4. Loop

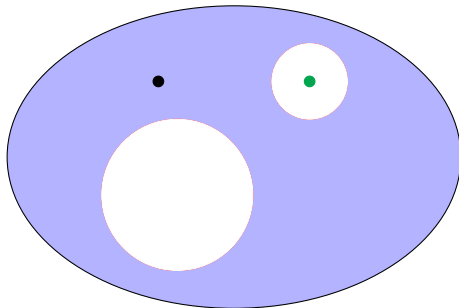


# A CEGAR-based algorithm

## Main algorithm

Takes  $\phi(\mathcal{X}, \mathcal{Y}, \mathcal{Z})$  as input and returns  $x_m$ .

1. Find an  $x$  candidate
2. Generalize it to a partial witness  $x|_{\mathcal{E}}$  such that  $|\phi(x|_{\mathcal{E}}, \mathcal{Y}, \mathcal{Z})|$  is close (from below) to the current maximum
3. Exclude the sub-space  $x|_{\mathcal{E}}$  from the future search
4. Loop

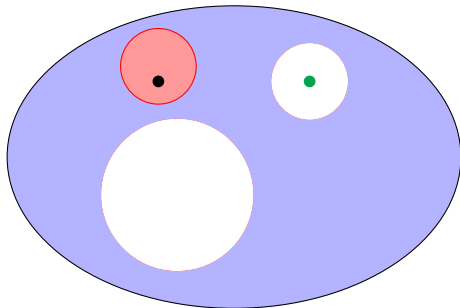


# A CEGAR-based algorithm

## Main algorithm

Takes  $\phi(\mathcal{X}, \mathcal{Y}, \mathcal{Z})$  as input and returns  $x_m$ .

1. Find an  $x$  candidate
2. *Generalize* it to a partial witness  $x|_{\mathcal{E}}$  such that  $|\phi(x|_{\mathcal{E}}, \mathcal{Y}, \mathcal{Z})|$  is close (from below) to the current maximum
3. Exclude the sub-space  $x|_{\mathcal{E}}$  from the future search
4. Loop

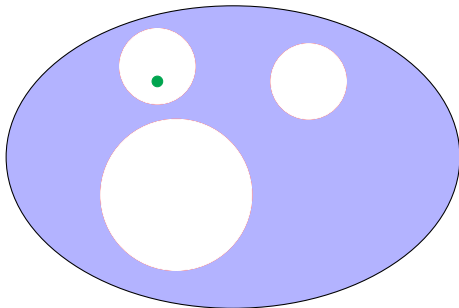


# A CEGAR-based algorithm

## Main algorithm

Takes  $\phi(\mathcal{X}, \mathcal{Y}, \mathcal{Z})$  as input and returns  $x_m$ .

1. Find an  $x$  candidate
2. *Generalize* it to a partial witness  $x|_{\mathcal{E}}$  such that  $|\phi(x|_{\mathcal{E}}, \mathcal{Y}, \mathcal{Z})|$  is close (from below) to the current maximum
3. **Exclude the sub-space**  $x|_{\mathcal{E}}$  from the future search
4. Loop



# A CEGAR-based algorithm

## Main algorithm

With  $\mathcal{X} = \{a, b\}$ ,  $\mathcal{Y} = \{c\}$ ,  $\mathcal{Z} = \{d\}$ :

$$\phi = (\neg a \vee c) \wedge (a \vee \neg b) \wedge (\neg b \vee d)$$

$x$	Generalization	Removed subspaces
$\neg a \wedge b$	$\neg a \wedge b$	$\{\neg a \wedge b\}$

# A CEGAR-based algorithm

## Main algorithm

With  $\mathcal{X} = \{a, b\}$ ,  $\mathcal{Y} = \{c\}$ ,  $\mathcal{Z} = \{d\}$ :

$$\phi = (\neg a \vee c) \wedge (a \vee \neg b) \wedge (\neg b \vee d)$$

$x$	Generalization	Removed subspaces
$\neg a \wedge b$	$\neg a \wedge b$	$\{\neg a \wedge b\}$
$a \wedge b$	$a$	$\{\neg a \wedge b, a\}$



# A CEGAR-based algorithm

## Main algorithm

With  $\mathcal{X} = \{a, b\}$ ,  $\mathcal{Y} = \{c\}$ ,  $\mathcal{Z} = \{d\}$ :

$$\phi = (\neg a \vee c) \wedge (a \vee \neg b) \wedge (\neg b \vee d)$$

$x$	Generalization	Removed subspaces
$\neg a \wedge b$	$\neg a \wedge b$	$\{\neg a \wedge b\}$
$a \wedge b$	$a$	$\{\neg a \wedge b, a\}$
$\neg a \wedge \neg b$	$\neg a \wedge \neg b$	$\{\neg a \wedge b, a, \neg a \wedge \neg b\}$

# A CEGAR-based algorithm

Generalizing candidates

## Key insight

Relaxing variables in a solution can only increase its model counting

# A CEGAR-based algorithm

## Generalizing candidates

### Key insight

Relaxing variables in a solution can only increase its model counting

Trial and error generalization:

- ▶ Try to release one variable from the solution:  $x|_{\mathcal{E}'}$
- ▶ If  $|\phi(x|_{\mathcal{E}'}, \mathcal{Y}, \mathcal{Z})|$  stays below the current maximum: use  $x|_{\mathcal{E}'}$  as the generalization from now on.

# A CEGAR-based algorithm

## Generalizing candidates

Generalization is an instance of a broader problem: *Minimal Subset to a Monotonous Predicate*.

Generic solvers exist:

- ▶ QUICKXPPLAIN<sup>1</sup>: recursively split the solution
- ▶ MERGEXPLAIN<sup>2</sup>: extend QUICKXPPLAIN to return multiple solutions

<sup>1</sup>Junker, “QuickXplain: Conflict detection for arbitrary constraint propagation algorithms”, 2001

<sup>2</sup>Shchekotykhin, Jannach, and Schmitz, “MergeXplain: Fast computation of multiple conflicts for diagnosis”, 2015

# A CEGAR-based algorithm

## Generalizing candidates

Generalization is an instance of a broader problem: *Minimal Subset to a Monotonous Predicate*.

Generic solvers exist:

- ▶ QUICKXPLAIN<sup>1</sup>: recursively split the solution
- ▶ MERGEXPLAIN<sup>2</sup>: extend QUICKXPLAIN to return multiple solutions

In our case, trial and error seems to be better.

<sup>1</sup>Junker, “QuickXplain: Conflict detection for arbitrary constraint propagation algorithms”, 2001

<sup>2</sup>Shchekotykhin, Jannach, and Schmitz, “MergeXplain: Fast computation of multiple conflicts for diagnosis”, 2015

# A CEGAR-based algorithm

## Theorems

### Theorem (Exact #SAT oracle)

*BAXMC is correct, i.e. always returns the actual maximum.*

### Theorem (Approximate #SAT oracle)

*BAXMC is probably approximately correct, i.e. returns the correct answer within a margin of  $\epsilon$ , with a probability of  $\delta$ .*

*Assuming that the #SAT oracle is correct within a margin of  $\epsilon'$  with a probability of  $\delta'$ .*

## Related works

MAXCOUNT<sup>1</sup>: amplification then sampling

d4max<sup>2</sup>: knowledge compilation to speed-up model counting

erssat<sup>3</sup>: more general problem, takes inspiration from *quantified boolean formulas*

<sup>1</sup>Fremont, Rabe, and Seshia, “Maximum model counting”, 2017

<sup>2</sup>Audemard, Lagniez, and Miceli, “A New Exact Solver for (Weighted) Max#SAT”, 2022

<sup>3</sup>Lee, Wang, and Jiang, “Solving Exist-Random Quantified Stochastic Boolean Satisfiability via Clause Selection”, 2018

## Some experimental results

Faster for approximate resolution on state-of-the-art benchmarks<sup>1</sup>:

Benchmark name	BAXMC	MAXCOUNT
backdoor-32-24*	34.50	231.87
backdoor-2x16-8*	60.02	6512.28
pwd-backdoor	236.87	TO
bin-search-16	1048.43	1490.44
CVE-2007-2875	36.14	TO
CVE-2009-3002	TO	MO
reverse	TO	MO

Yields better results in nearly all cases.

<sup>1</sup>Fremont, Rabe, and Seshia, "Maximum model counting", 2017



## Extensions of this algorithm

Implemented optimizations:

- ▶ Symmetry breaking
- ▶ Equivalent literals handling

# Extensions of this algorithm

Implemented optimizations:

- ▶ Symmetry breaking
- ▶ Equivalent literals handling

Simple heuristic to prioritize search:

1. When overapproximating the count of a subspace, it may be **above the current maximum**
2. It may contain promising **witnesses**
3. **Focus** the future search in these areas

## Future works

On BAXMC resolution:

- ▶ Incremental
- ▶ Parallel
- ▶ Extend to solve stochastic SAT<sup>1</sup> instances

<sup>1</sup>Lee, Wang, and Jiang, "Solving Exist-Random Quantified Stochastic Boolean Satisfiability via Clause Selection", 2018

# Future works

On BAXMC resolution:

- ▶ Incremental
- ▶ Parallel
- ▶ Extend to solve stochastic SAT<sup>1</sup> instances

On optimizing search:

- ▶ Better symmetry breaking
- ▶ Leads scheduling

<sup>1</sup>Lee, Wang, and Jiang, "Solving Exist-Random Quantified Stochastic Boolean Satisfiability via Clause Selection", 2018

## Future works

On BAXMC resolution:

- ▶ Incremental
- ▶ Parallel
- ▶ Extend to solve stochastic SAT<sup>1</sup> instances

On optimizing search:

- ▶ Better symmetry breaking
- ▶ Leads scheduling

Actually use this in a security setting.

<sup>1</sup>Lee, Wang, and Jiang, "Solving Exist-Random Quantified Stochastic Boolean Satisfiability via Clause Selection", 2018

## Take-home message

- ▶ New solver for  $\text{Max}\#\text{SAT}$
- ▶ Two solving modes: exact and approximate
- ▶ Better experimental performances

Docker and sources available at:

<https://www-verimag.imag.fr/~vigourth/research/baxmc/>

@VERIMAG (Grenoble):

- ▶ Professorship
- ▶ Tenured full-time research positions
- ▶ Possibilities of post-docs

ask David Monniaux (in audience)

# Bootstrapping the search

Idea:

1. Search for a good solution *fast* using a different method
2. Start BAXMC with the values found by the earlier method

# Bootstrapping the search

Idea:

1. Search for a good solution *fast* using a different method
2. Start BAXMC with the values found by the earlier method

Consequences:

- ▶ The result is at least better
- ▶ Guarantees about the optimality of the results



## References

-  Audemard, Gilles, Jean-Marie Lagniez, and Marie Miceli. “A New Exact Solver for (Weighted) Max#SAT”. In: *25th International Conference on Theory and Applications of Satisfiability Testing, SAT 2022, August 2-5, 2022, Haifa, Israel*. Ed. by Kuldeep S. Meel and Ofer Strichman. Vol. 236. LIPIcs. Schloss Dagstuhl - Leibniz-Zentrum für Informatik, 2022, 28:1–28:20. DOI: 10.4230/LIPIcs.SAT.2022.28. URL: <https://doi.org/10.4230/LIPIcs.SAT.2022.28>.
-  Fremont, Daniel, Markus Rabe, and Sanjit Seshia. “Maximum model counting”. In: *Proceedings of the AAAI Conference on Artificial Intelligence*. Vol. 31. 1. 2017.
-  Junker, Ulrich. “QuickXplain: Conflict detection for arbitrary constraint propagation algorithms”. In: *IJCAI01 Workshop on Modelling and Solving problems with constraints*. Vol. 4. Citeseer. 2001.
-  Lee, Nian-Ze, Yen-Shi Wang, and Jie-Hong R. Jiang. “Solving Exist-Random Quantified Stochastic Boolean Satisfiability via Clause Selection”. In: *Proceedings of the Twenty-Seventh*