ACORN: Network Control Plane Abstraction using Route Nondeterminism

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Network design



Protocol + Configuration Routing protocols RIP, OSPF, BGP, ...

Forwarding Tables

Runtime Behavior

Network control plane



- The origin sends an initial route announcement
- On receiving a route announcement:
 - a router processes it as per the configurations
 - selects the best route announcement received
 - forwards the selected one to its neighbors, after processing it
- At convergence, the network will be in a *stable state*

Network misconfigurations are common

How a coding error caused Rogers outage that left millions without

service

ALEXANDRA POSADZKI >

Major Fastly outage brings down much of the Internet: Amazon, Twitch, Reddit, and more offline

PUBLISHED JULY 25, 2022

The Verge, The Guardian, and others go offline

June 08, 2021 By: Sebastian Moss 🔘 Comment

A Cloudflare outage broke large swathes of the internet

Jun 21, 2022

BGP super-blunder: How Verizon today sparked a 'cascading catastrophic failure' that knackered Cloudflare, Amazon, etc

'Normally you'd filter it out if some small provider said they own the internet'

Kieren McCarthy in San Francisco Mon 24 Jun 2019 // 19:01 UTC

Microsoft: Misconfigured Network Device Caused Azure Outage

A misconfigured network device caused Thursday's outage for the Windows Azure cloud computing platform, Microsoft said Friday. The downtime left the Azure Compute service unavailable to cstomers in some parts of Europe for more than two hours.

Network verification

Properties



Reachability



Valley-free





Control plane verifiers

port 5

- analyze router configurations that determine the forwarding rules
- have limited scalability, especially SMT-based approaches



- analyze a snapshot of the network given forwarding rules •
- scale to large networks (\approx 10,000 routers) ٠

Goal: Improve scalability

Solve an *abstract* verification problem

Abstract certain network features while preserving soundness

SMT encoding

Symbolic graph-based encoding Use SMT solvers with specialized theories, e.g. MonoSAT [Bayless et al. AAAI 2015]

Abstract the route selection procedure

• Best route is not always needed to verify properties (e.g., reachability)

- Selected route should comply with network policy
- => Continue to model route filters *precisely*
- Modeling route selection is expensive
 - Especially for complex policy-based routing protocols like BGP
 - One main difference between data plane and control plane
 - => Get closer to performance of data plane verifiers by abstracting route selection

Example: Verifying reachability

Network N Each router selects the best route



a has a route to **d**

Abstract network N' Each router selects any route



Example: Verifying reachability

Network N Each router selects the best route



a has a route to **d**

For more precision, we define a *hierarchy* of abstractions



Background: Stable Routing Problem (SRP)

 $(G, A, a_d, \prec, trans)$



SRP solutions $\mathcal{L}: V \to A_{\infty}$ represent stable states at convergence

[Beckett et al. SIGCOMM 2018]

Formalizing NRC abstractions via abstract SRP

(G, A, a_d, ≺', trans)



SRP solutions $\mathcal{L}: V \to A_{\infty}$ represent stable states at convergence

Soundness of NRC abstractions

Abstract SRP S'over-approximates corresponding SRP S

Theorem: Any solution of S, $\mathcal{L}: V \to A_{\infty}$ is a solution of S'Proof uses the requirement that the minimal route according to \prec is also minimal according to \prec'

SMT-based verification with NRC abstraction



Goal: Improve scalability

Solve an *abstract* **verification problem** Abstract certain network features while preserving soundness

SMT encoding

Symbolic graph-based encoding Use SMT solvers with specialized theories, e.g. MonoSAT [Bayless et al. AAAI 2015]

Background: MonoSAT SMT solver

- SMT solver with support for graph-based reasoning
- Uses symbolic graphs, graphs with a Boolean variable per edge



Symbolic graph $G_{RE} = (G, RE)$ G = (V, E) $RE = \{re_{uv} \mid (u, v) \in E\}$ Reachability predicate: G_{RE} . reaches(u, v)

Formula F over RE and other variables, with graph predicates like reachability Satisfying assignment corresponds to a subgraph of G (symbolic graph solution)

[Bayless et al. AAAI 2015]

Symbolic graph-based encoding

Encode abstract SRP S' with SMT formula N' Symbolic graph solutions = solutions of abstract SRP S'

Four types of constraints:

- 1. Routing choice constraints
- 2. Route availability constraints
- 3. Attribute transfer and route filtering constraints
- 4. Solver-specific constraints for route availability Reachability predicate used in MonoSAT

Symbolic graph-based encoding

Routing choice constraints

Each node u chooses a neighbor v or None

$$\left(\bigvee_{(v,u)\in E} nChoice_{u} = nID(u,v)\right) \lor nChoice_{u} = None_{u}$$
$$nChoice_{u} = nID(u,v) \leftrightarrow re_{vu}$$
Symbolic edge
variable

Benefits of NRC and graph-based encoding

• Fewer variables

Route announcement fields used only in route selection are discarded Community attribute (in BGP) sufficient for most policies evaluated

• Expensive transfers can become irrelevant during solver search

Once a symbolic edge variable is assigned true, other neighbors become irrelevant Without abstraction, computing the best route requires transfers from all neighbors

ACORN prototype implementation



Evaluation

- 1. Relative performance of NRC abstractions (with / without)
- 2. Relative performance of graph theory capable SMT solver (MonoSAT / Z3)

Four experiment settings:

- abs_mono: NRC abstraction using MonoSAT
- abs_z3: NRC abstraction using Z3
- mono: no abstraction using MonoSAT
- z3: no abstraction using Z3

Benchmarks

- Data center examples with FatTree topology (to evaluate scalability)
 Synthetic benchmarks with shortest-path and valley-free policies
- 2. Wide Area Network (WAN) examples with real-world topologies
 - Topology zoo examples, which we annotated with business relationships
 - BGPStream examples, annotated using the CAIDA AS relationships dataset

All our benchmarks are publicly available:

https://github.com/divya-urs/ACORN_benchmarks

Machine details: 2.3 GHz Intel i7 processor, 16 GB RAM

FatTree network with valley-free policy



c = 2: route has 2 Aggr nodes

c = 3: route has \geq 3 Aggr nodes

Results for FatTrees with valley-free policy



Abstract settings verify both properties without false positives Abstraction improves performance in *all* networks (up to 52x speedup for MonoSAT) **abs_mono verifies reachability for a FatTree with 36,980 routers in 40 mins**

Results for BGPStream examples



Abstract settings verify *no-transit property* in **all** networks Abstract settings verify *reachability* in **6/10** networks Remaining 4/10 are verified using a more precise abstraction

Comparison with other tools



Reachability (single-src) on FatTree benchmarks with valley-free policy

- NV uses MTBDD-based simulation and SMT
- ShapeShifter uses BDD-based simulation with abstract interpretation
- NV and ShapeShifter *run out of memory* for networks with > 3000 nodes
- ACORN scales to ≈37,000 nodes for reachability

Summary

- Nondeterministic Routing Choice (NRC) abstraction hierarchy Formalized using the SRP model and proved sound for verification
- Symbolic graph-based SMT encoding

Leverages SMT solvers with graph theory support as well as standard SMT solvers

 NRC abstractions can verify realistic policies and improve scalability Could verify reachability for ≈37,000 routers within an hour